



INTERNATIONAL MICRO AIR VEHICLE CONFERENCE AND FLIGHT COMPETITION 2017

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Proceedings

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Preface

This volume contains the papers presented at IMAV2017: International Micro Air Vehicles Conference and Flight Competition 2017.

The International Micro Air Vehicle Conference and Competition is a yearly event that aims at fostering key technologies for the development of micro-air vehicles. It combines a scientific conference and a flight competition intended to all research groups around the world. After Delft (2014), Aachen (2015) and Beijing (2016), this year edition was held in Toulouse, France, from September 18th to 21nd, 2017.

This edition was, again, an occasion to put forward the methodological and technological advances in this rapidly growing field. The impressive variety of application cases, related needs, and breakthroughs has been represented through the papers gathered in this volume. These papers address many challenges, among which one may mention:

- Conception for new configurations, more efficient, easier to manufacture, bio-inspired,...
- Aerodynamics studies to reduce consumption or to improve drones performances, or to perform finer simulations
- Aeroacoustics studies to reduce the noise produced by drones
- Human machine cooperation, a domain where impressive progress is ongoing, which helps to better understand the human brain, and reduce the operator workload
- Improving the control and guidance designs, in particular to allow multi-vehicles cooperation, better trajectory tracking, and wind gusts rejection, collision avoidance, consumption reduction, or load carrying
- Navigation, the capability to localize the drone in complex environments, with a degraded set of sensors, in particular with the use of few information, for example vision only
- Artificial intelligence, decision making in uncertain contexts, which helps the embedded system taking relevant and safe decision in dynamic environments
- Atmospheric wind measurements

This volume shows great achievements in these various areas. Among those high quality papers, the program committee would like to mention that the paper entitled “Quad-thopter: Tailless Flapping Wing Robot with 4 Pairs of Wings” by Christophe De Wagter, Matej Karasek and Guido de Croon have been nominated for the *Best Paper Award*.

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Toulouse

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List of Papers

Session SA1: Aerodynamics and flow control

Qualitative Investigation of the Dynamics of a Leading Edge Control Surfaces for Micro Air Vehicle Applications	1
<i>Ashim Panta, Phred Petersen, Simon Watkins, Matthew Marino, Abdulghani Mohamed and A Fisher</i>	
Aerodynamic design of a Martian micro air vehicle	9
<i>Thibault Désert, Jean-Marc Moschetta and Hervé Bezar</i>	
Study of ducted fans interference for copter type multirotor UAV/RPAS	17
<i>Kirill Stremousov and Maxim Arkhipov</i>	

Session SB1: Control designs and analysis for MAVs

A numerical approach for attitude control of a quadrotor	23
<i>Huu-Phuc Nguyen, Jérôme De Miras, Ali Charara and Stéphane Bonnet</i>	
Application of a switching control strategy to extract energy from turbulence by a UAV	29
<i>Yves Briere, Federico Pasquali and Nikola Gavriovic</i>	
Prioritized Control Allocation for Quadrotors Subject to Saturation	37
<i>Ewoud Smeur, Daan Höppener and Christophe de Wagter</i>	

Session SA2: Aero-acoustics investigations

Aeroacoustics investigation on nano coaxial rotor in hover	44
<i>Zhen Liu, Chen Bu, Xiangxu Kong and Dong Yang</i>	
Reducing the noise of Micro-Air Vehicles in hover	51
<i>Ronan Serre, Vincent Chapin, Jean-Marc Moschetta and Hugo Fournier</i>	
Application of Lattice Boltzmann Method to some challenges related to Micro Air Vehicles	60
<i>Nicolas Gourdain, Thierry Jardin, Ronan Serre, Sébastien Prothin and Jean-Marc Moschetta</i>	

Session TA1: Control designs and analysis

Controller Tuning Strategy for Quadrotor MAV Carrying a Cable-suspended Load	89
<i>Nestor Alonso Santos Ortiz, Sylvain Durand, Renaud Kiefer and Edouard Laroche</i>	
Landing and Take-off on/from Sloped and Non-planar Surfaces with more than 50 Degrees of Inclination	97
<i>Marco Tognon and Antonio Franchi</i>	
Flight Simulation of a MAKO UAV for Use in Data-Driven Fault Diagnosis	103
<i>Elgiz Baskaya, Murat Bronz and Daniel Delahaye</i>	
Incremental Nonlinear Dynamic Inversion and Multihole Pressure Probes for Disturbance Rejection Control of Fixed-wing Micro Air Vehicles	111
<i>Elisabeth van der Sman, Ewoud Smeur, Bart Remes, Christophe De Wagter and Qiping Chu</i>	

Session TB1: Navigation strategies and the use of vision

Human-Robot Cooperation in Surface Inspection Aerial Missions	121
<i>Martin Molina, Pedro Frau, Dario Maravall, Jose Luis Sanchez-Lopez, Hriday Bavle and Pascual Campoy</i>	
An Intelligent Unmanned Aircraft System for Wilderness Search and Rescue	129
<i>Huai Yu, Shijie Lin, Jinwang Wang, Kaimin Fu and Wen Yang</i>	
A honeybee's navigational toolkit on Board a Bio-inspired Micro Flying Robot	136
<i>Erik Vanhoutte, Franck Ruffier and Julien Serres</i>	
Loosely Coupled Stereo Inertial Odometry on Low-cost System	143
<i>Haochih Lin and François Defaï</i>	

Session SA3: Novel designs for MAVs

Investigation on Natural Frequency and Fuselage Effect for Small UAVs Lateral Motion	149
<i>Mostafa El-Salamony and Sergey Serokhovostov</i>	
Team MAVion entry in the IMAV'17 outdoor challenge – A tail-sitting trajectory-tracking uUAV	156
<i>Leandro R. Lustosa, Jacson Miguel Olszanecki Barth, Jean-Philippe Condomines, Francois Defay and Jean-Marc Moschetta</i>	
Simulation and Control of a Tandem TiltWing RPAS Without Experimental Data	162
<i>Yannic Beyer, Thomas Krüger, Arne Krüger, Meiko Steen and Peter Hecker</i>	

Session SB3: Wind measurements or rejection

Using MAVs for Atmospheric Wind Measurements: Opportunities and Challenges	170
<i>Simon Watkins, Mohamed Abdulghani, Sam Prudden, Matthew Marino, Reece Clothier, Alex Fisher and Ashim Panta</i>	
Bio-inspired Wind Field Estimation-Part 1: AoA Measurements Through Surface Pressure Distribution	175
<i>Nikola Gavrilovic, Murat Bronz, Jean-Marc Moschetta, Emmanuel Benard and Philippe Pastor</i>	
Developing a Stable Small UAS for Operation in Turbulent Urban Environments	184
<i>Rohan Gigacz, Abdulghani Mohamed, Pakorn Poksawat, Simon Watkins and Ashim Panta</i>	

Session TA2: Multiple vehicles cooperation

Collision Avoidance of multiple MAVs using a multiple Outputs to Input Saturation Technique	190
<i>Corentin Chauffaut, Laurent Burlion, François Defaï and Henry de Plinval</i>	
A Combined Approach for 3D Formation Control in a Multi-UAV System using ROS	196
<i>Rafael Braga, Alexandre Carlos Brandao Ramos, Roberto Claudino Da Silva and Félix Mora-Camino</i>	
Formation flight of fixed-wing aircraft by employing guidance vector fields	203
<i>Hector Garcia De Marina and Gautier Hattenberger</i>	
EDURA: an Evolvable Demonstrator for Upset Recovery Approaches with a 3D-printed Launcher	209
<i>Torbjørn Cunis and Murat Bronz</i>	

Session TB2: Novel design methodologies for MAVs

Optimization of Energy Consumption for Quadrotor UAV	215
<i>Fouad Yacef, Nassim Rizoug, Omar Bouhali and Mustapha Hamerlain</i>	
Development and Design Methodology of an Anti-Vibration System on Micro-UAVs	223
<i>Zhenming Li, Mingjie Lao, Swee King Phang, Mohamed Redhwan Abdul Hamid, Kok Zuea Tang and Feng Lin</i>	
Quick aerodynamic design of micro air vehicles	229
<i>Atem Kislovskiy and Viktor Vyshinsky</i>	
Copter size minimization for the IMAV-2017 competition in Record breaking session	235
<i>Boris Makaev and Sergey Serokhovostov</i>	

Session SA4: Specific MAVs designs: flapping and folding wings, and bio-inspired designs

Bond Graph based design tool for a passive rotation flapping wing	242
<i>Le Anh Doan, Sebastien Grondel, Eric Cattan and Christophe Delebarre</i>	
Quad-thopter: Tailless Flapping Wing Robot with 4 Pairs of Wings.	249
<i>Christophe De Wagter, Matej Karasek and Guido de Croon</i>	
Analysis of Folding Wing Rolling Moment	257
<i>N Krajangsawasdi, T Pantuphag, S Catteeyothai and Chinnapat Thipyopas</i>	

Session SB4: Image processing developments

Development of Vision Based Navigation for Micro Aerial Vehicles in Harsh Environment	263
<i>Hailong Qin, Yingcai Bi, Feng Lin and Ben M Chen</i>	
Efficient Global Indoor Localization for Micro Aerial Vehicles	270
<i>Volker Strobel, Roland Meertens and Guido de Croon</i>	
3D Reconstruction of Complex Structures with Online Profiling and Adaptive Viewpoint Sampling	278
<i>Abdullah Abduldayem, Dongming Gan, Lakmal Seneviratne and Tarek Taha</i>	
An Automated Rapid Mapping Solution Based on ORBSLAM and Agisoft Photoscan API	286
<i>Markus Bobbe, Alexander Kern, Yogesh Khedar, Simon Batzdorfer and Ulf Bestmann</i>	

Poster session

Investigation on Boundary layer Ingestion Propulsion for UAVs	293
<i>Leonid Teperin, Mostafa El-Salamony, Ahmed Moharam and Moamen Shehata</i>	
Multidisciplinary optimization of a MAV propeller for noise reduction	301
<i>Franck Boyer, Arnaud Drapier, Yann Merillac, Cyril Nana and Ronan Serré</i>	
Propeller Performance Calculation for Multirotor Aircraft at Forward Flight Conditions and Validation with Wind Tunnel Measurements	307
<i>Christian Molter and Po Wen Cheng</i>	

Author Index

Abdul Hamid, Mohamed Redhwan	223
Abduldayem, Abdullah	278
Abdulghani, Mohamed	170
Arkipov, Maxim	17
Baskaya, Elgiz	103
Batzdorfer, Simon	286
Bavle, Hriday	121
Benard, Emmanuel	175
Bestmann, Ulf	286
Beyer, Yannic	162
Bezard, Hervé	9
Bi, Yingcai	263
Bobbe, Markus	286
Bonnet, Stéphane	23
Bouhali, Omar	215
Boyer, Franck	301
Braga, Rafael	196
Briere, Yves	29
Bronz, Murat	103, 175, 209
Bu, Chen	44
Burlion, Laurent	190
Campoy, Pascual	121
Cattan, Eric	242
Catteeyothai, S	257
Chapin, Vincent	51
Charara, Ali	23
Chauffaut, Corentin	190
Chen, Ben M	263
Cheng, Po Wen	307
Chu, Qiping	111
Claudino Da Silva, Roberto	196
Clothier, Reece	170
Condomines, Jean-Philippe	156
Cunis, Torbjørn	209
De Croon, Guido	270, 249
De Miras, Jérôme	23
de Plinval, Henry	190
De Wagter, Christophe	37, 111, 249
Defay, Francois	156
Defay, François	143, 190
Delahaye, Daniel	103
Delebarre, Christophe	242
Doan, Le Anh	242

Drapier, Arnaud	301
Durand, Sylvain	89
Désert, Thibault	9
El-Salamony, Mostafa	149, 293
Fisher, A	1
Fisher, Alex	170
Fournier, Hugo	51
Franchi, Antonio	97
Frau, Pedro	121
Fu, Kaimin	129
Gan, Dongming	278
Garcia De Marina, Hector	203
Gavrilovic, Nikola	175
Gavriovic, Nikola	29
Gigacz, Rohan	184
Gourdain, Nicolas	60
Grondel, Sebastien	242
Hamerlain, Mustapha	215
Hattenberger, Gautier	203
Hecker, Peter	162
Höppener, Daan	37
Jardin, Thierry	60
Karasek, Matej	249
Kern, Alexander	286
Khedar, Yogesh	286
Kiefer, Renaud	89
Kislovskiy, Atem	229
Kong, Xiangxu	44
Krajangsawasdi, N	257
Krüger, Arne	162
Krüger, Thomas	162
Lao, Mingjie	223
Laroche, Edouard	89
Li, Zhenming	223
Lin, Feng	223, 263
Lin, Haochih	143
Lin, Shijie	129
Liu, Zhen	44
Lustosa, Leandro R.	156
Makaev, Boris	235
Maravall, Dario	121
Marino, Matthew	1, 170
Meertens, Roland	270
Merillac, Yann	301
Mohamed, Abdulghani	1, 184
Moharam, Ahmed	293
Molina, Martin	121
Molter, Christian	307
Mora-Camino, Félix	196
Moschetta, Jean-Marc	9, 51, 60, 156, 175

Nana, Cyril	301
Nguyen, Huu-Phuc	23
Olszanecki Barth, Jacson Miguel	156
Panta, Ashim	1, 170, 184
Pantuphag, T	257
Pasquali, Federico	29
Pastor, Philippe	175
Petersen, Phred	1
Phang, Swee King	223
Poksawat, Pakorn	184
Prothin, Sébastien	60
Prudden, Sam	170
Qin, Hailong	263
Ramos, Alexandre Carlos Brandao	196
Remes, Bart	111
Rizoug, Nassim	215
Ruffier, Franck	136
Sanchez-Lopez, Jose Luis	121
Santos Ortiz, Nestor Alonso	89
Seneviratne, Lakmal	278
Serokhvostov, Sergey	149, 235
Serre, Ronan	51, 60
Serres, Julien	136
Serré, Ronan	301
Shehata, Moamen	293
Smeur, Ewoud	37, 111
Steen, Meiko	162
Stremousov, Kirill	17
Strobel, Volker	270
Taha, Tarek	278
Tang, Kok Zuea	223
Teperin, Leonid	293
Thipyopas, Chinnapat	257
Tognon, Marco	97
van der Sman, Elisabeth	111
Vanhoutte, Erik	136
Vyshinsky, Viktor	229
Wang, Jinwang	129
Watkins, Simon	1, 170, 184
Yacef, Fouad	215
Yang, Dong	44
Yang, Wen	129
Yu, Huai	129

